

/ Perfect Welding / Solar Energy / Perfect Charging



Joachim Danmayr, Fabian Neubacher  
Fronius International GmbH  
Froniusplatz 1, 4600 Wels

**MODULAR SOFTWARE ARCHITECTURE AND SYSTEM TESTING  
IN THE PROCESS ENGINEERING SECTORS  
FOR PRODUCING GREEN HYDROGEN**



Hydrogen Technology  
First Solhub  
2018



Charging  
Three phase charger  
2013

Hydrogen Technology  
Start Hydrogen research  
2002



Perfect welding  
Digitalization  
1998

Founded  
1945

Welding technologies  
Welding Robots  
2015

Perfect welding  
CMT technology  
2005

Solar energy  
New inverter technologies  
2001

Solar energy  
First solar inverter  
1995





Founded new Team for  
hydrogen research and  
development  
2019

Hydrogen intra-  
logistics at BMW  
2017



Wind to hydrogen  
2015

Start with hydrogen  
technology research  
2002

HySnow research project  
2020

Solhub prototype  
2018



Energy self-  
sufficient house  
2012

Hydrogen in intralogistics  
2007



Joachim Danmayr

University of Hagen  
Computer Science  
2013 -

JKU Linz  
Technical physics  
2009 - 2010

HTL Steyr  
Electronics  
2002 - 2007

Fronius  
technical lead  
software development  
hydrogen systems  
2019 -

Fronius  
software architect  
embedded systems  
solar inverter  
2015 - 2019

Fronius  
hard- and software developer  
power electronics control  
solar inverter  
2008 - 2015



Fabian Neubacher

University of Applied Sciences  
Upper Austria  
**Human-centered Computing**  
**(MSc)**  
2017 - 2019

University of Applied Sciences  
Upper Austria  
**Medical Engineering (BSc)**  
2011 - 2014

HTL Vöcklabruck  
**Machine and Plant**  
**Engineering**  
2005 - 2010

Fronius  
**Technical lead**  
**testsystem development**  
hydrogen systems  
2019 -

Novartis  
**Project Manager Engineering**  
**Qualification Engineer**  
NTO - Aseptics  
2016 - 2019

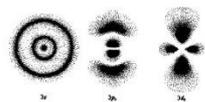
Austrian Red Cross  
**Emergency Paramedic**  
Vöcklabruck  
2015 - 2016



Testing

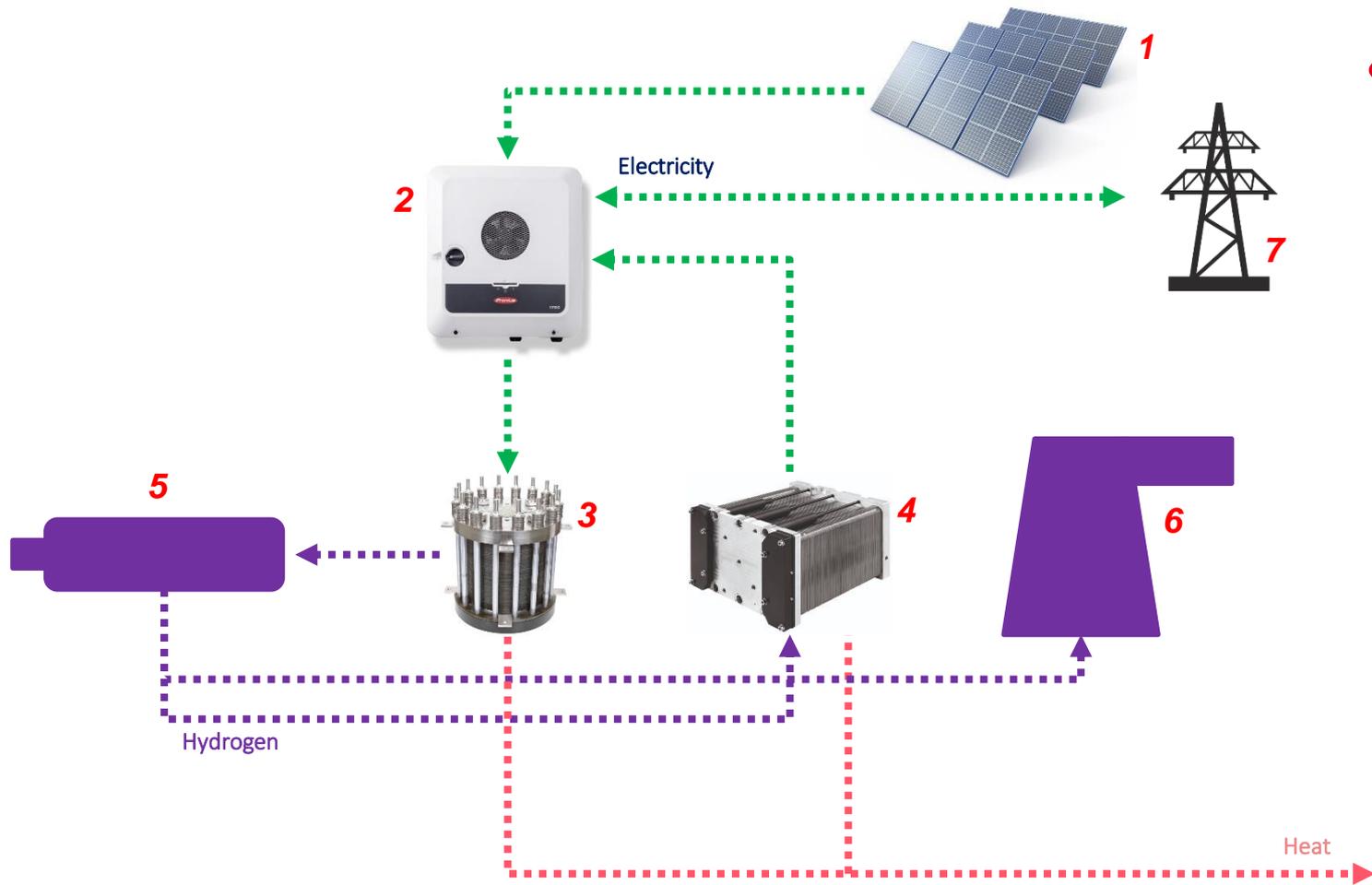
Microservices

**Overview**

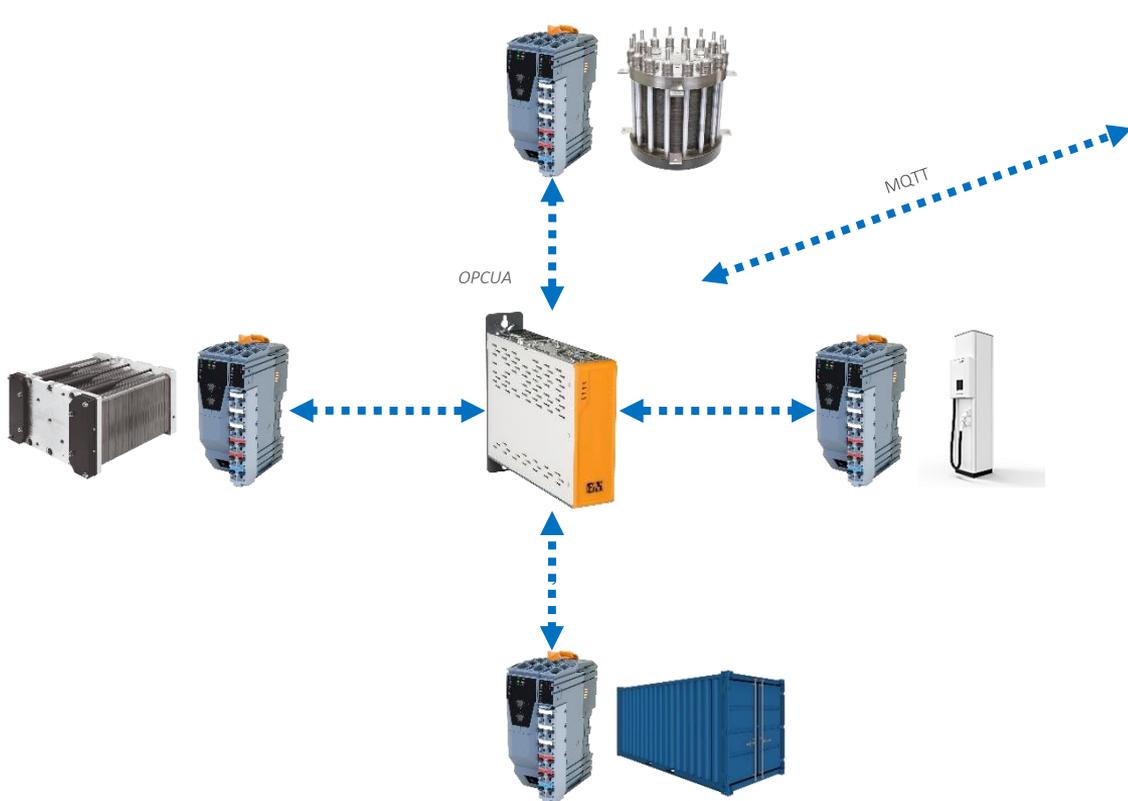


# SOLHUB



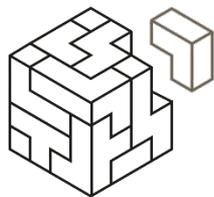


- 1. Photovoltaics
- 2. Inverter
- 3. Electrolyzer
- 4. Fuel Cell
- 5. Hydrogen storage
- 6. Dispenser
- 7. Grid



- Modular system design with centralized IPC and cloud connection.
- Goal to bring the complexity to the IPC

- Classically the main functions are implemented in PLCs.
- We are focused on outsourcing most of the functionality to the IPC.
- The IPC has a microservice based architecture design which allows us to develop evolutionary.

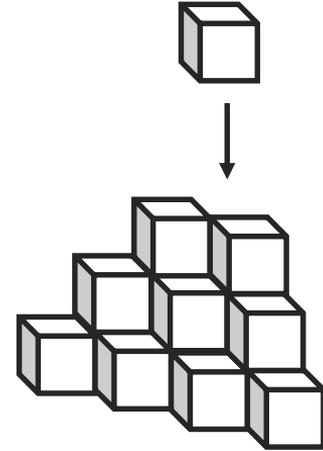


# MICROSERVICES

## What is a microservice and why we need it?



**microservices** | also known as the **microservice** architecture - is an architectural style that structures an application as a collection of services that are highly **maintainable** and **testable**, **loosely coupled** and **independently** deployable. [1]

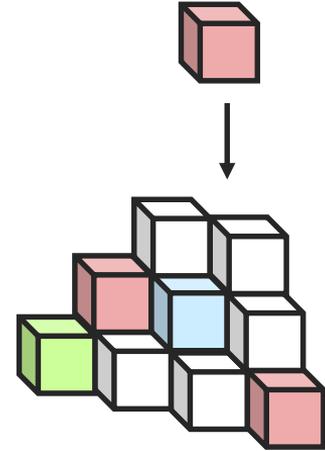


[1] What are microservices? (2020), microservices.io, <https://microservices.io/>

## What is a microservice and why we need it?

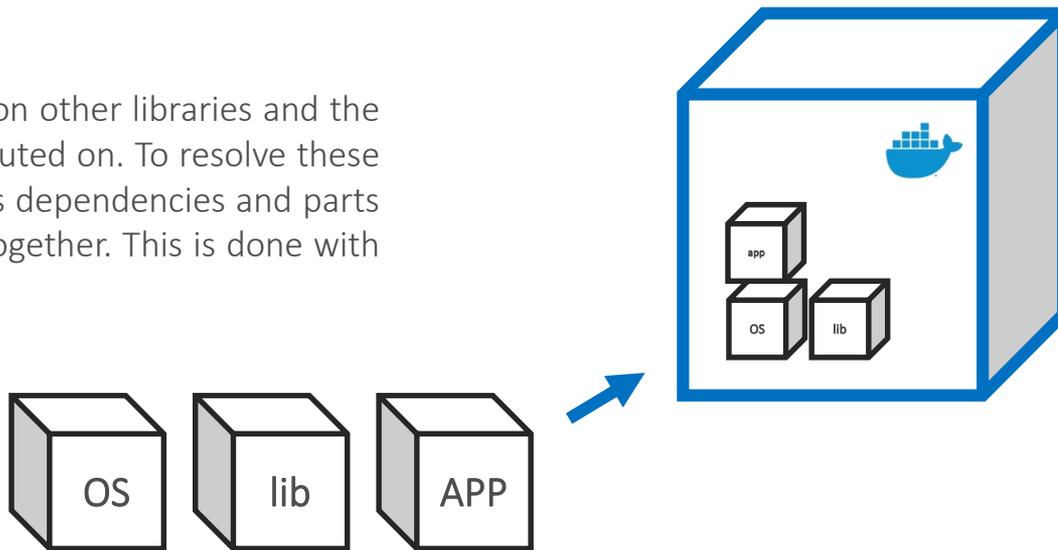


**advantages** | complex systems can be divided into little, less complex components. These components can be developed independently from each other and put together later on.



## How to get such independent loosely coupled software components?

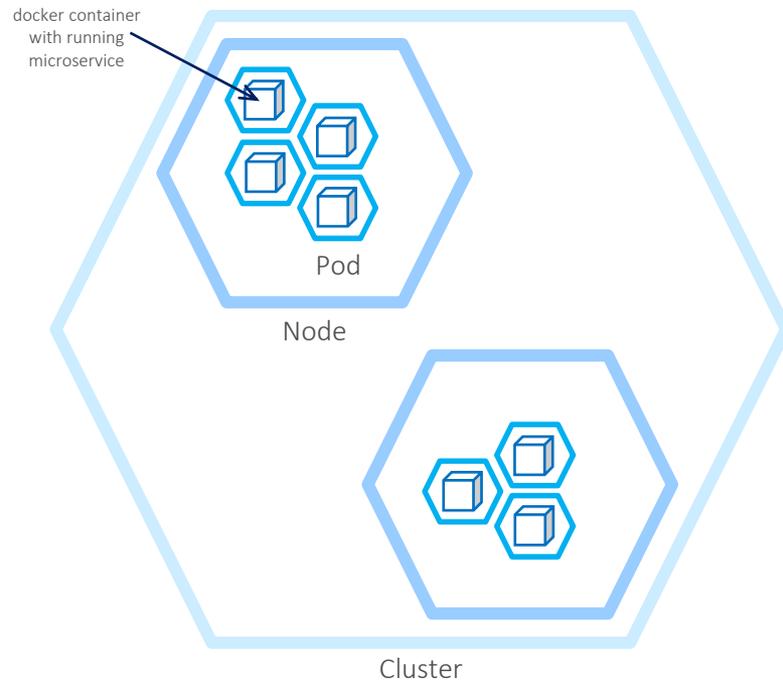
**docker** | software programs depends on other libraries and the operating system the program is executed on. To resolve these dependencies the program with all its dependencies and parts of the operating system are packed together. This is done with so called docker images.



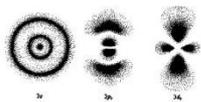
```
>> docker build
```

## How to execute and manage these docker images?

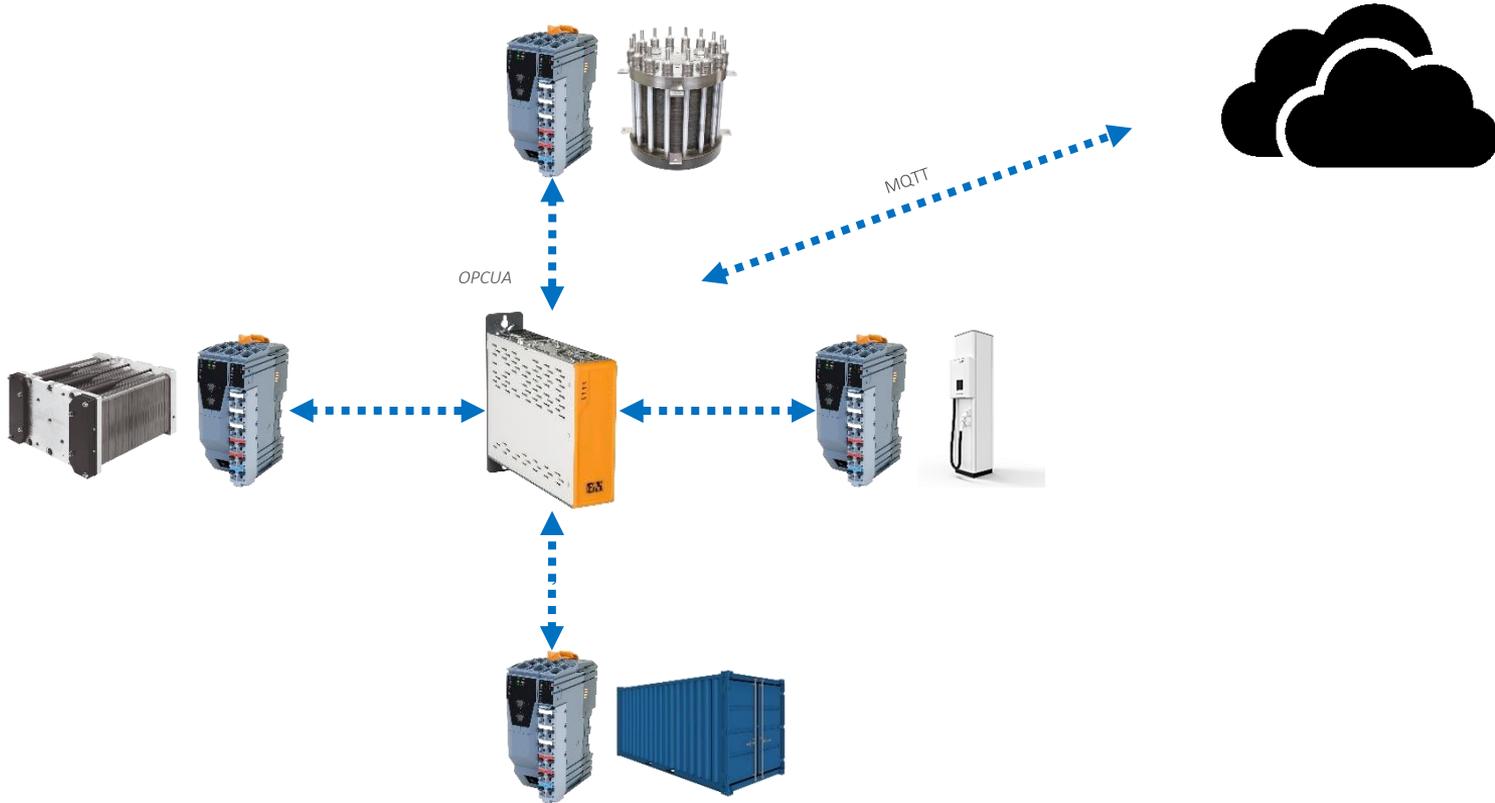
**kubernetes** | now the microservices are packed into images. For deployment, executing and monitoring kubernetes is used. With kubernetes docker images can be started and stopped as well as updated. Kubernetes allows to create clusters which manage load balancing.



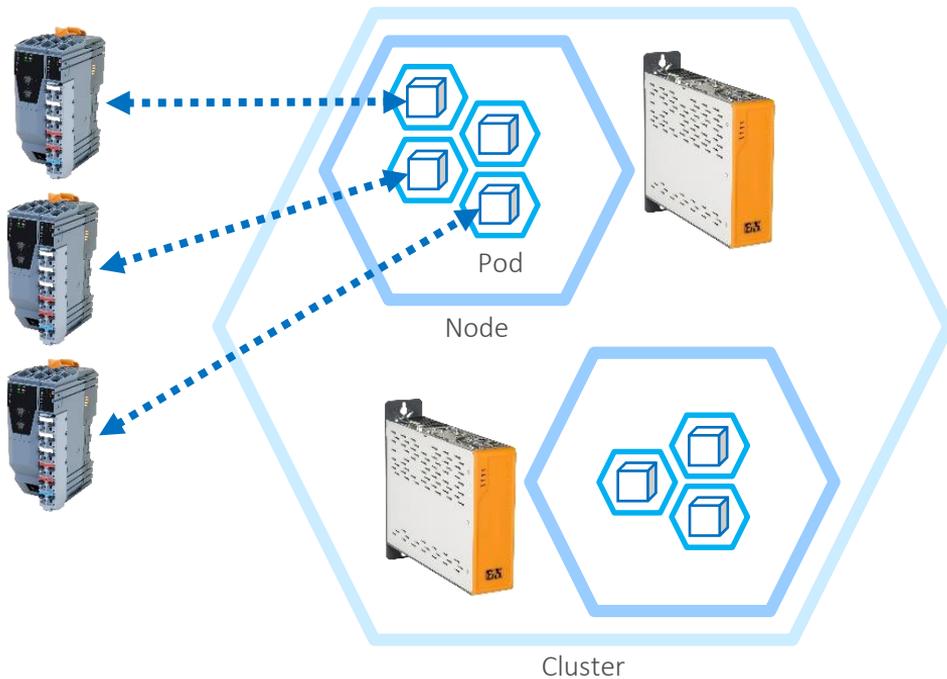
```
>> kubectl apply -f myDeployment.yaml
```



# SOLHUB

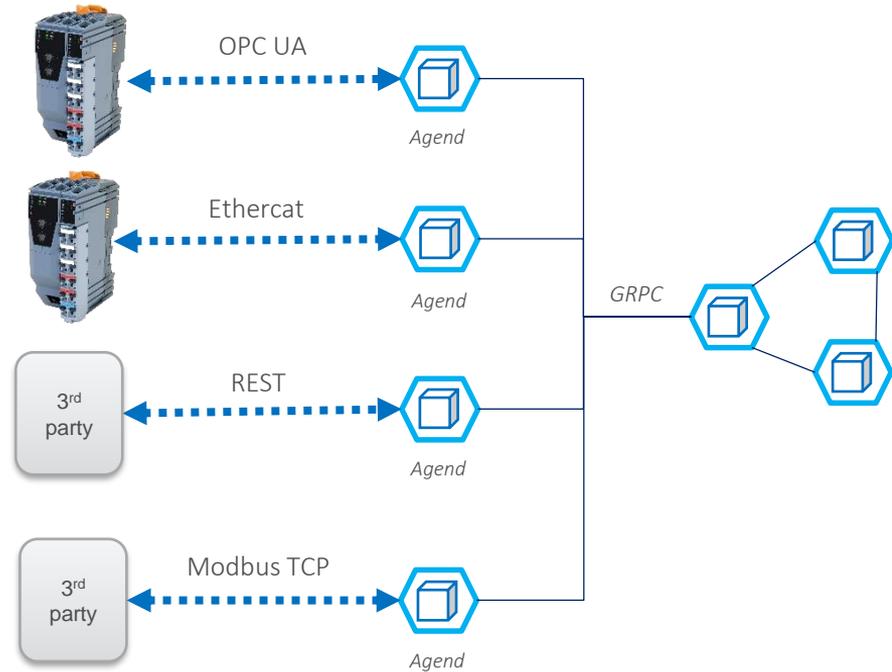


# Standalone hydrogen system...

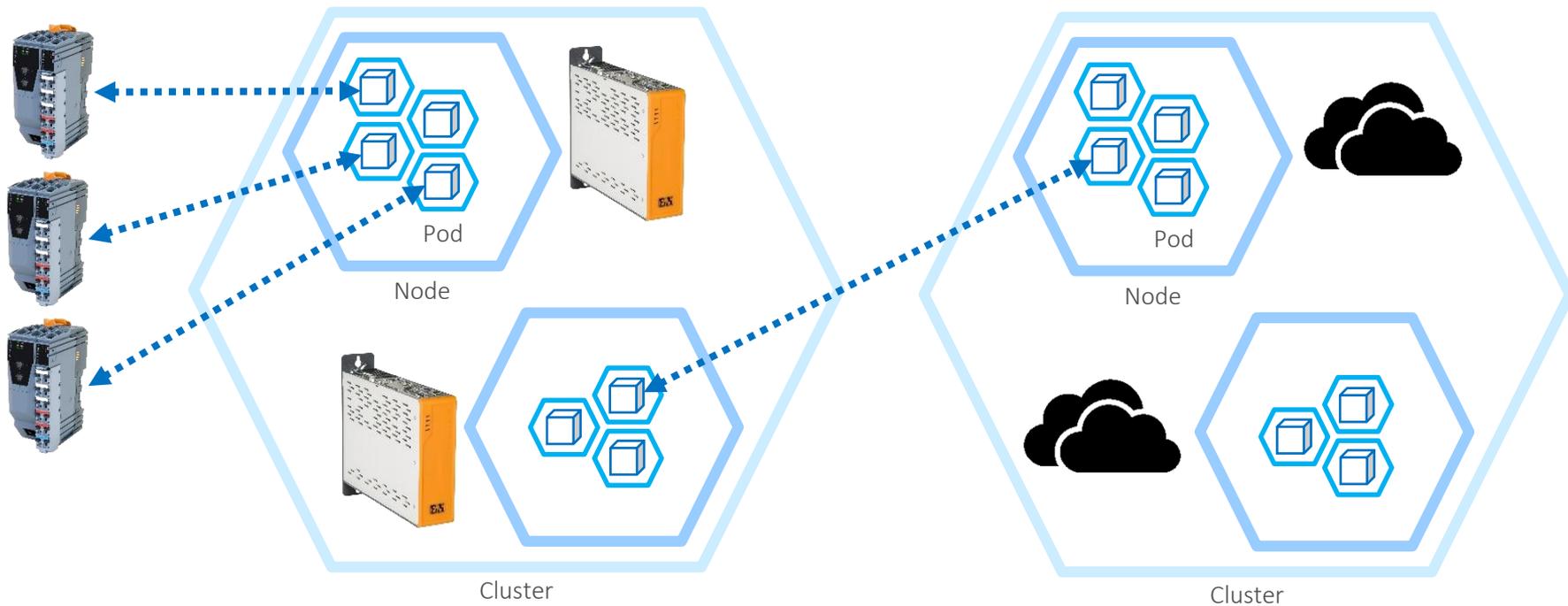


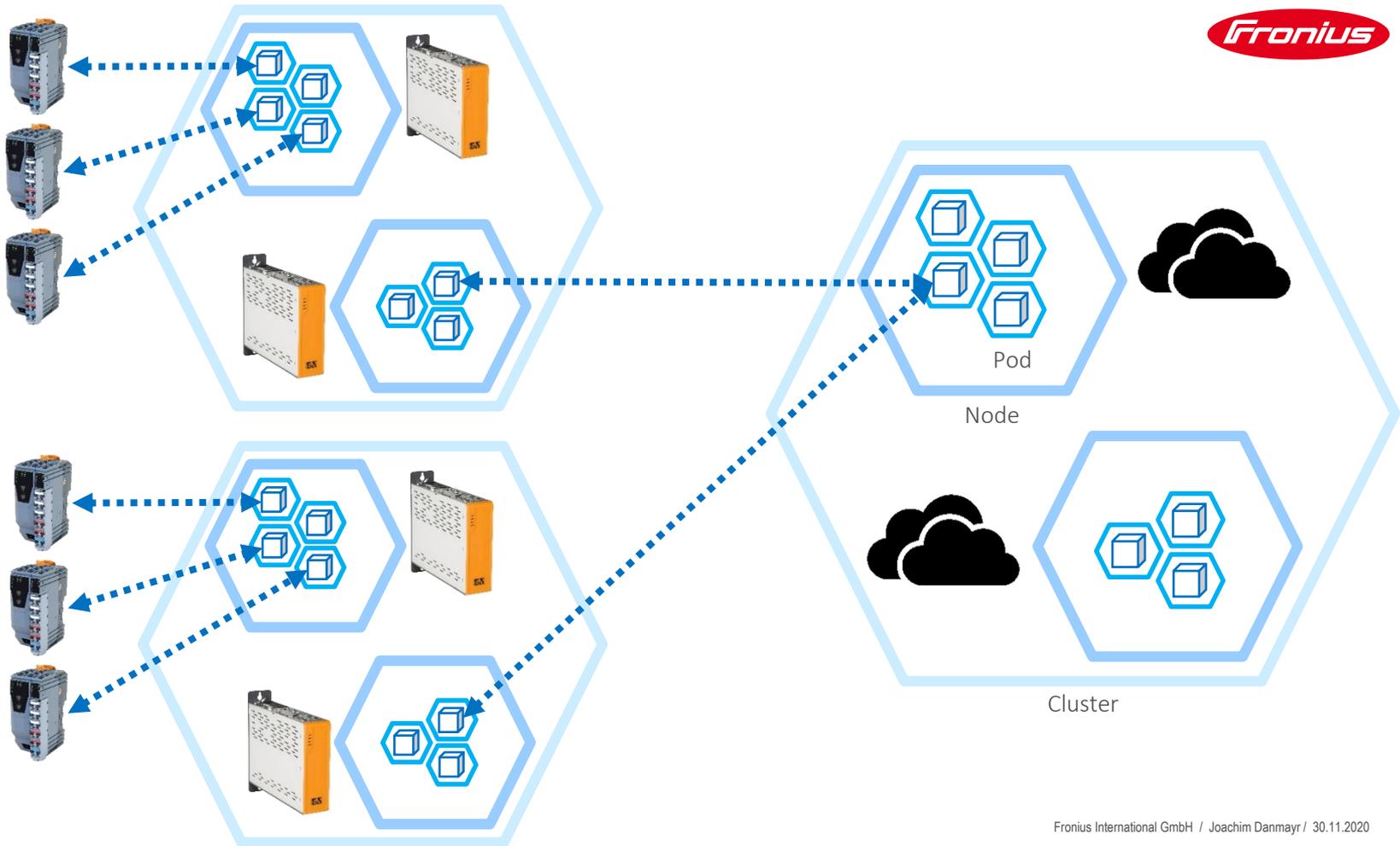
Solhub

**agend** | agend microservices are used for representing an embedded system as microservice in the high level system.

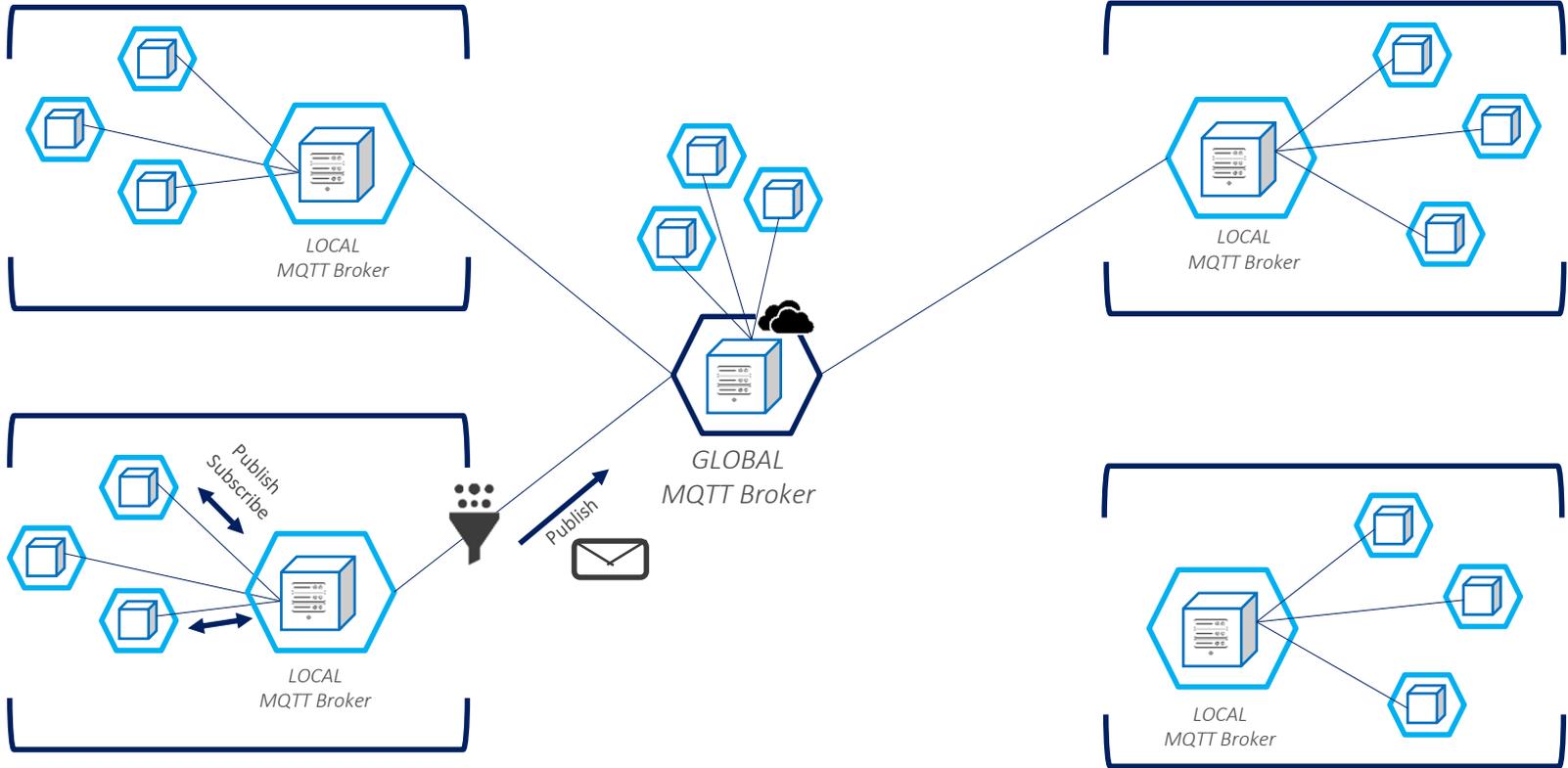


Connection to cloud...

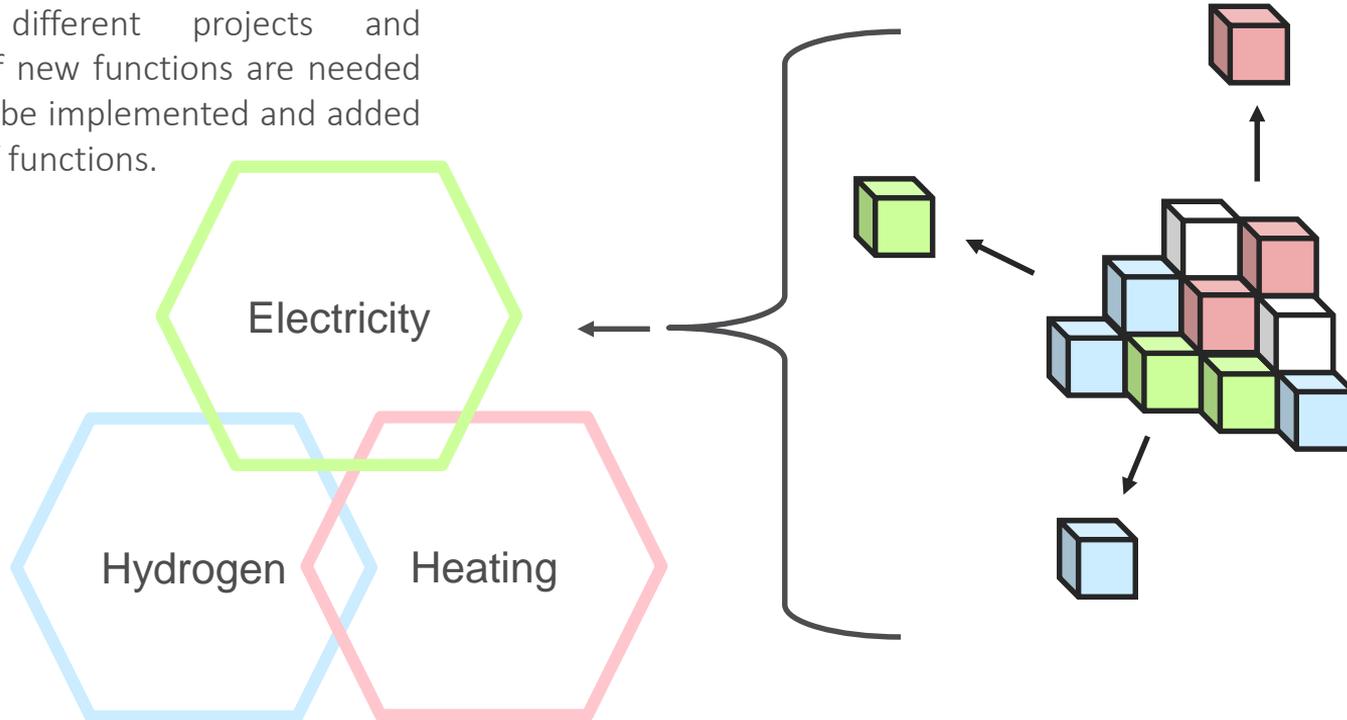




# MQTT ...

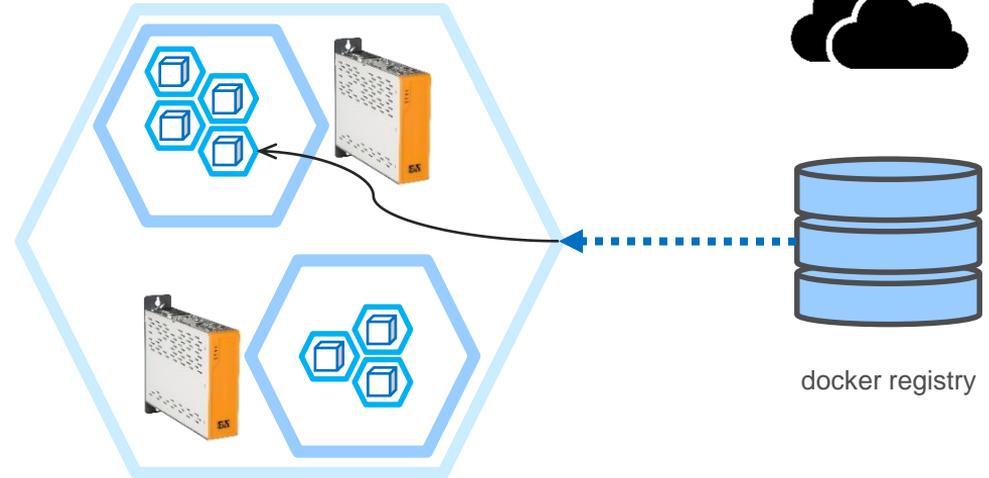


reusability| the microservices can be used for different projects and application. If new functions are needed they can just be implemented and added to the pool of functions.

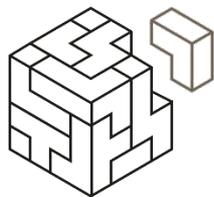


## How does this work?

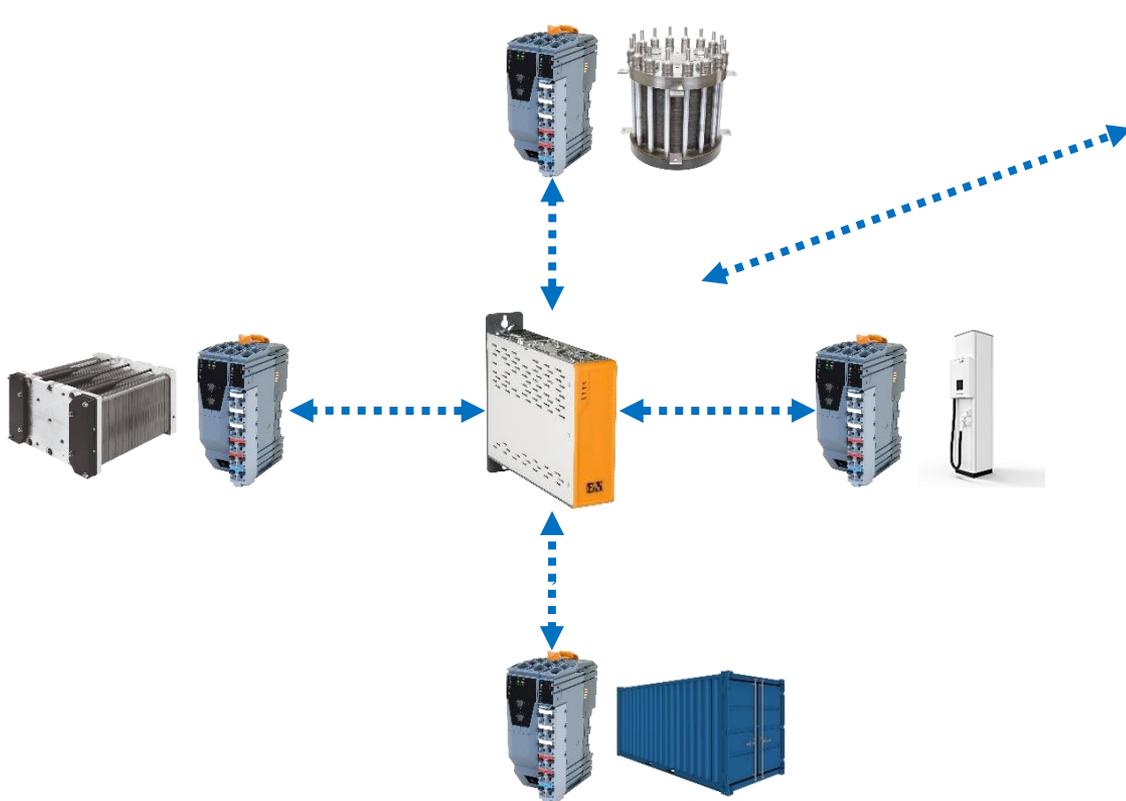
**registry** | there is a centralized Fronius docker registry in the cloud. This registry can be accessed from all Fronius devices. The registry contains all available microservices. Kubernetes downloads the needed images from this registry and starts the contains within its cluster.



```
>> docker pull
```



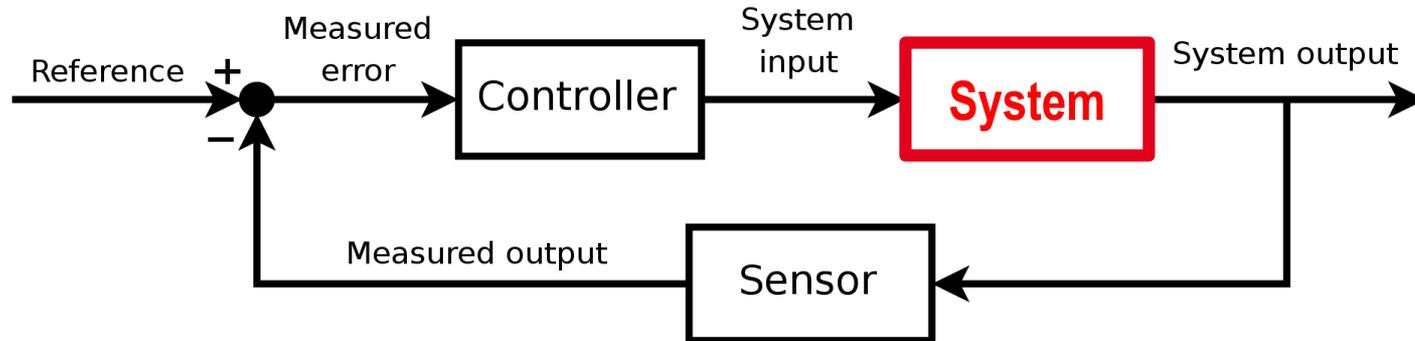
# SYSTEM TESTING



- Modular system design with centralized IPC and cloud connection.
- Goal to bring the complexity to the IPC

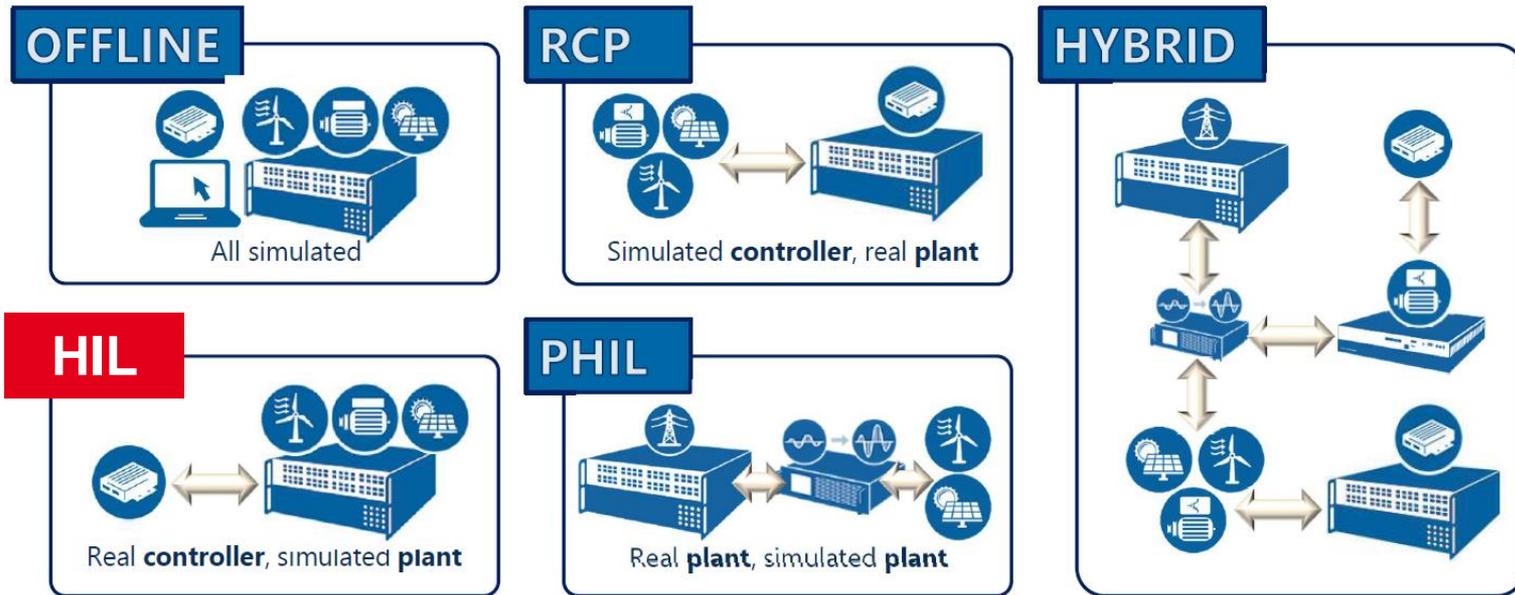
## *BASICS: HIL-SYSTEM*

- HIL = Hardware in the loop
- QA for software controlled components according to 61508
- Real controller / simulated system



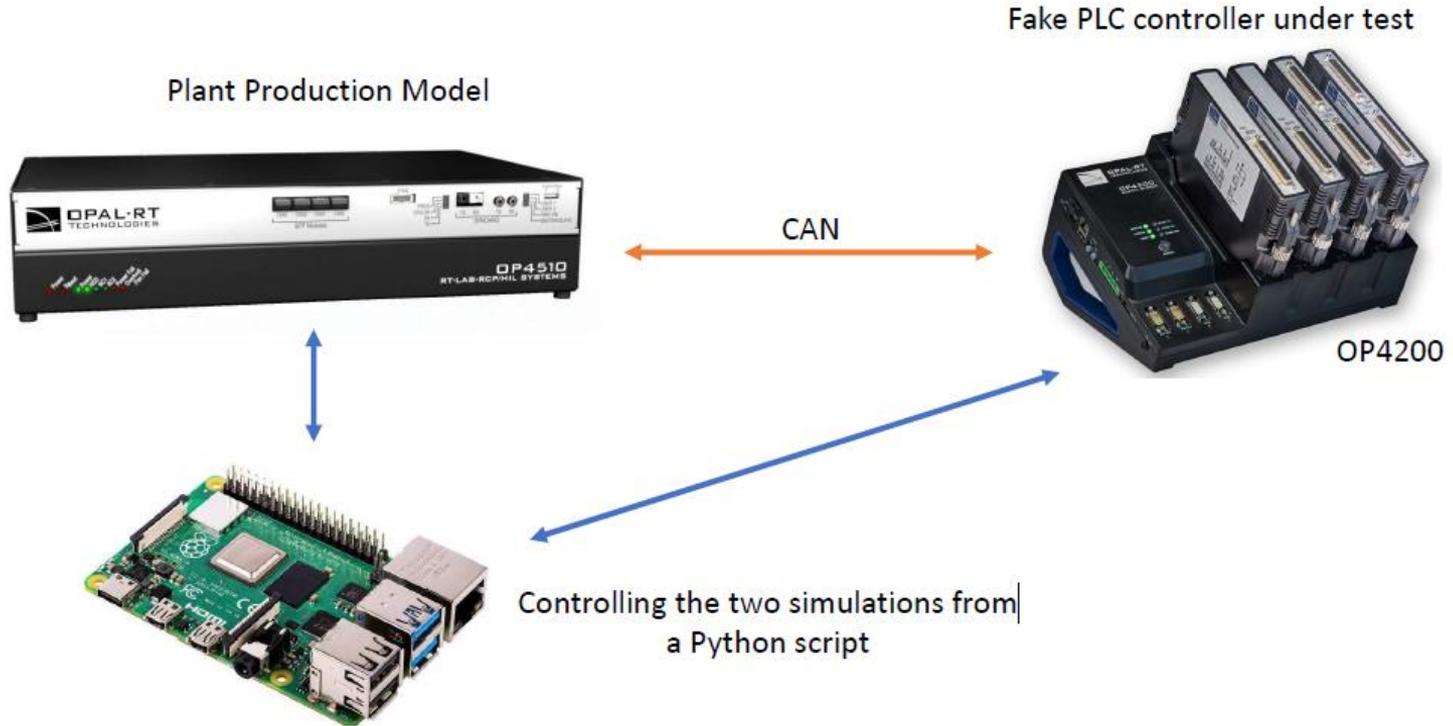


## OPAL-RT SYSTEM



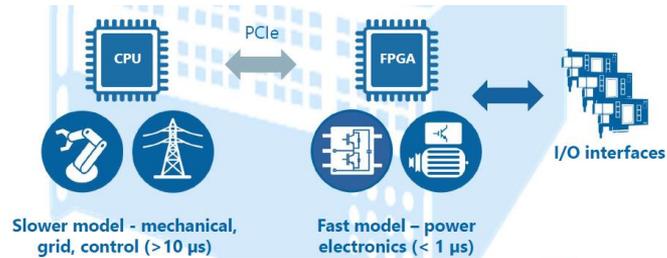
FROM IMAGINATION... TO REAL-TIME

## ACTUAL STRUCTURE



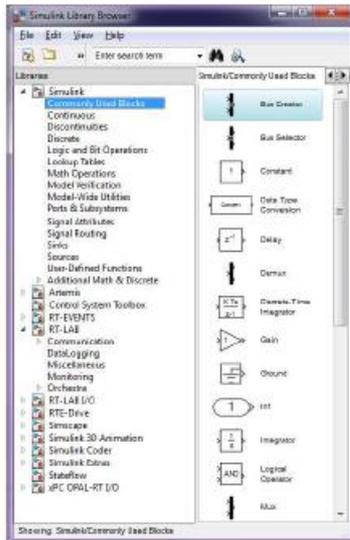
## ACTUAL STRUCTURE

Simulation environment:  
Matlab/Simulink, Simscape



FROM IMAGINATION... TO REAL-TIME

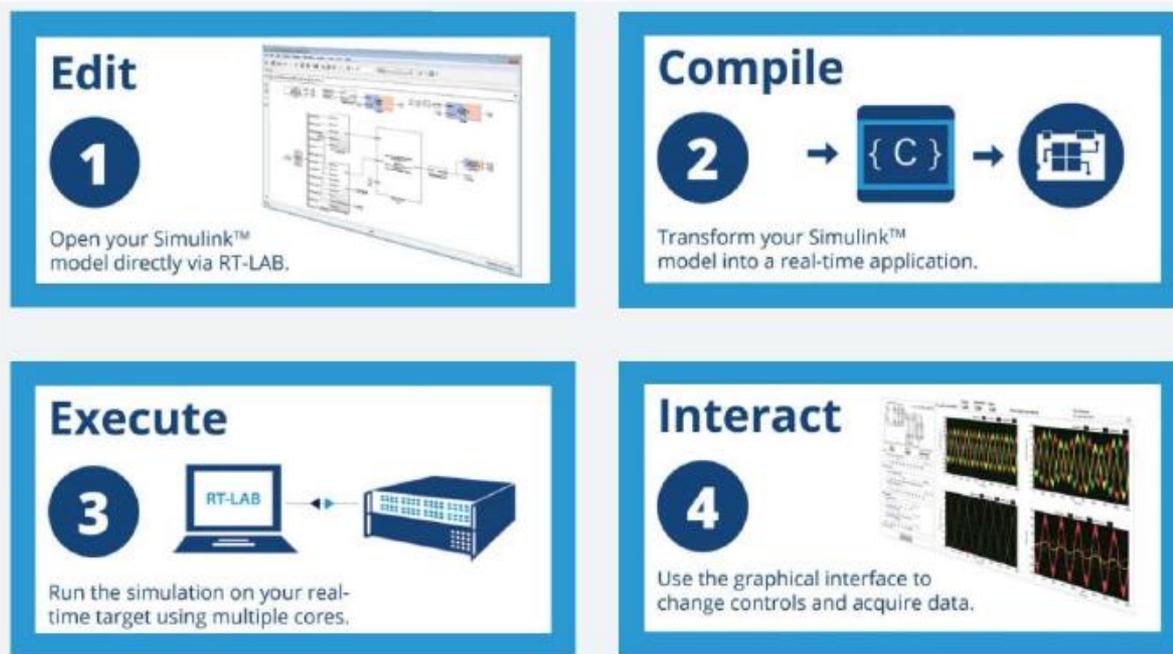
OPAL-RT TECHNOLOGIES



This section contains five distinct diagrams illustrating simulation models:

- Physical models:** A detailed schematic of a mechanical system with an engine, gears, and a flywheel, connected to a control system and a power source.
- Electrical systems:** A complex circuit diagram showing various electrical components, including resistors, capacitors, inductors, and power sources, interconnected in a network.
- State diagrams:** A block diagram showing a sequence of state transitions between different system states, with associated logic and data flow.
- Code:** A snippet of MATLAB code defining a discrete-time system with a transfer function and a sampling period.
- Algorithms:** A block diagram representing a control algorithm, featuring integrators, gain blocks, and feedback loops.

## FROM MODEL TO REAL TIME



FROM IMAGINATION... TO REAL-TIME



## CE-COMPLIANT TEST ARCHITECTURE

AREA	DESIGN	VERIFICATION	TEST
HIL (OPAL-RT Rack)	I/O Table including sampling rate	Factory calibration Design verification	Qualification Recalibration
Signal Conditioning	Requirements	Initial calibration	Recalibration
OPAL-RT Lab (Software)	Standards Proven on the market	NA	Newest release (maintenance agreement)
Mathworks --> C	Proven on the market State of the art	Code review (sample)	Newest release (maintenance agreement)
Models	Tracing back to physical and mathematical principles	Review (comparison with measured data)	Operation within defined limits
	Derivation from measured data	Review	Operation within defined limits
Test - Programs	Styleguides	Review	Implicit in test execution

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